

REMARKS

The claims have been amended to more clearly define the invention as disclosed in the written description. In particular, claim 19 has been made a proper singularly dependent claim depending from claim 13. In addition, the claims have been amended for clarity.

When the Examiner takes this case up for examination, it is respectfully requested that this Preliminary Amendment be taken into consideration.

Respectfully submitted,

by 
Edward W. Goodman, Reg. 28,613
Attorney
Tel.: 914-333-9611

FINGERPRINTED - PG00000000000000000000000000000000

APPENDIX

1. (Amended) **METHOD** A method for detecting motion at a temporal intermediate position between previous and next images, in which a criterion function for candidate vectors is optimised optimized, said function depending on data from both 5 previous and next images and in which the optimising optimizing is carried out at the temporal intermediate position in non-covering and non-uncovering areas, characterised characterized in that the optimising optimizing is carried out at the temporal position of the next image in covering areas and at the temporal position of 10 the previous image in uncovering areas.

10

2. (Amended) ~~Method according to~~The method as claimed in claim 1, wherein the previous image is shifted over a fraction α times the candidate vector, the next image is shifted over $1 - \alpha$ times the candidate vector and the fraction α may change within the image period.

3. (Amended) ~~Method according to The method as claimed in~~
claim 1, wherein the criterion function is a match error which is
minimised.

4. (Amended) ~~Method according to~~ The method as claimed in
claim 2, wherein the fraction α is controlled by a
covering/uncovering detector in the matching process.

5. (Amended) ~~Method according to~~ The method as claimed in
claim 4, wherein the fraction α is set to 1 in case of covering and
set to 0 in case of uncovering.

6. (Amended) ~~Method according to~~ The method as claimed in
claim 4, wherein the covering/uncovering detector decides on data
in a previous image to the fraction α in the current estimation.

7. (Amended) ~~Method according to~~ The method as claimed in
claim 1, wherein a velocity edge X_E is determined, an occlusion
area is marked around said edge, and in said occlusion area,
foreground velocity is replaced by background velocity or
reversibly dependent on whether the occlusion area is a covering or
uncovering area, the sign of the foreground velocity and on which
side of the velocity edge X_E the foreground is.

8. (Amended) ~~Method according to~~ The method as claimed in
claim 7, wherein at the position \vec{x}_i of a velocity edge

- a first position \vec{x}_a in the previous (covering) or next (uncovering) image is calculated by shifting \vec{x}_1 over the first vector at one side of the edge
- 5 • a second position \vec{x}_b in the previous (covering) or next (uncovering) image is calculated by shifting \vec{x}_1 over the second vector at the other side of the edge
- 10 • and a third intermediate position between \vec{x}_a and \vec{x}_b is calculated
- while finally, the vector fetched with $v_{\bar{a}v}$ at the third position in the previous (covering) or next (uncovering) image is filled in those regions of the image in the environment of the edge, to which no vector is projected, in case the background vector $v_{\bar{B}G} \underline{v_{\bar{F}G}}$ should be filled in, and the vector chosen between $\bar{D}(\vec{x} - \begin{pmatrix} 1 \\ 0 \end{pmatrix}, n)$ and $\bar{D}(\vec{x} + \begin{pmatrix} 1 \\ 0 \end{pmatrix}, n)$ which is most different from $v_{\bar{a}v}$ is filled in, in case a foreground vector $v_{\bar{F}G}$ should be filled in.

9. (Amended) ~~Method according to The method as claimed in~~
claim 8, wherein the intermediate position is $(\vec{x}_a + \vec{x}_b)/2$.

10. (Amended) ~~Method according to The method as claimed in~~
claim 7, wherein a background velocity is identified as a velocity

which crosses the velocity discontinuity and projects to a foreground velocity in the previous picture, whereas a foreground 5 velocity projects to itself.

11. (Amended) ~~Method according to~~ The method as claimed in claim 7, wherein near edges it is tested whether the mentioned edge has moved over the first vector on one side of the edge, or over the second vector on the other side of the edge, in case the edge 5 moves with the first (second) vector, the second (first) vector is filled in those regions of the projected vector field in the environment of the edge, to which no vector is projected, in case a background vector v_{BG} should be filled in, and the other vector is filled in, in case a foreground vector v_{FG} should be filled.

12. (Amended) ~~Method according to~~ The method as claimed in claim 10, wherein the crossing from a background region to a foreground region in the previous image is verified by the match error of the vector in that block.

13. (Amended) ~~Apparatus~~ An apparatus for detecting motion at a temporal intermediate position between previous and next images, comprising means ~~(1)~~ optimising for optimizing a criterion function for candidate vectors, said function depending on data from both 5 previous and next images in which the ~~optimising~~ optimizing is

carried out at the temporal intermediate position in non-covering and non-uncovering areas, characterised characterized in that said apparatus further comprises means for detection detecting covering or uncovering areas, wherein (2) are provided and that the 10 optimising optimizing is carried out at the temporal position of the next image in covering areas and at the temporal position of the previous image in uncovering areas.

14. (Amended) Apparatus according to The apparatus as claimed in claim 13, wherein the previous image is shifted over a fraction α times the candidate vector, the next image is shifted over $1 - \alpha$ times the candidate vector and the fraction α may change within the image period.

15. (Amended) Apparatus according to The apparatus as claimed in claim 13, wherein the criterion function is a match error which is minimised minimized.

16. (Amended) Apparatus according to The apparatus as claimed in claim 14, wherein said apparatus further comprises a covering/uncovering detector for controlling the fraction α is controlled by a covering/uncovering detector (2) in the matching process.

17. (Amended) ~~Apparatus according to~~ The apparatus as claimed
in claim 16, wherein the fraction α is set to 1 in case of covering
and set to 0 in case of uncovering.

18. (Amended) ~~Apparatus according to~~ The apparatus as claimed
in claim 16, wherein the covering/uncovering detector ~~(2)~~ decides
on data in a previous image to the fraction α in the current
estimation.

19. (Amended) ~~Apparatus according to one of the preceding~~
~~claims~~ The apparatus as claimed in claim 13, wherein a velocity edge
 X_E is determined, an occlusion area is marked around said edge, and
in said occlusion area, foreground velocity is replaced by
background velocity or reversibly dependent on whether the
occlusion area is a covering or uncovering area, the sign of the
foreground velocity and on which side of the velocity edge X_E the
foreground is.

20. (Amended) ~~Apparatus according to~~ The apparatus as claimed
in claim 19, wherein said apparatus further comprises calculation
means ~~(5,6,8)~~ are provided for, at the position \vec{x}_1 of a velocity
edge, calculating

5 • a first position \vec{x}_a in the previous (covering) or next
(uncovering) image by shifting \vec{x}_1 over the first vector at one side
of the edge

10 • a second position \vec{x}_b in the previous (covering) or next
(uncovering) image by shifting \vec{x}_1 over the second vector at the
other side of the edge

15 • and a third intermediate position between \vec{x}_a and \vec{x}_b ,
• while finally, the vector fetched with $v_{\bar{a}v}$ at the third position
in the previous (covering) or next (uncovering) image (9) is filled
in those regions of the image in the environment of the edge, to
which no vector is projected, in case the background vector $v_{\bar{B}G} \underline{v_{\bar{F}G}}$
should be filled in, and the vector chosen between $\bar{D}(\vec{x} - \begin{pmatrix} 1 \\ 0 \end{pmatrix}, n)$ and
 $\bar{D}(\vec{x} + \begin{pmatrix} 1 \\ 0 \end{pmatrix}, n)$ which is most different from $v_{\bar{a}v}$ is filled in, in case a
foreground vector $v_{\bar{F}G}$ should be filled in.

21. (Amended) Apparatus according to The apparatus as claimed
in claim 20, wherein the intermediate position is $(\vec{x}_a + \vec{x}_b)/2$.

22. (Amended) Apparatus according to The apparatus as claimed
in claim 19, wherein said apparatus further comprises means

(10,11) are provided for projecting two positions on either side of the edge to the previous (covering) or next (uncovering) image, in which a background velocity is identified ~~(14)~~ as a velocity which crosses the velocity discontinuity and projects to a foreground velocity in the previous picture, whereas a foreground velocity projects to itself.

23. (Amended) Apparatus according to The apparatus as claimed in claim 19, wherein said apparatus further comprises means ~~(20)~~ are provided for testing near edges whether the mentioned edge has moved over the first vector on one side of the edge, or over the second vector on the other side of the edge, in case the edge moves with the first (second) vector, the second (first) vector is filled in those regions of the projected vector field in the environment of the edge, to which no vector is projected, in case a background vector v_{BG} should be filled in, and the other vector is filled in, in case a foreground vector v_{FG} should be filled.

24. (Amended) Apparatus according to The apparatus as claimed in claim 22, wherein said apparatus further comprises verification means are provided for verifying the crossing from a background region to a foreground region in the previous image by the match error of the vector in that block.

25. (Amended) ~~Image~~ An image display apparatus comprising
detection apparatus (21) for detection detecting a motion vector
according to as claimed in claim 13, means (22) for interpolating
image parts connected to said ~~detection~~ detecting apparatus, (21)
5 and a display device (23) connected to the interpolating means.

05855628-051501